## Exercise 90

Let $\left\{\left(U_{\alpha}, \phi_{\alpha}\right)\right\}$ be a collection of charts such that the open sets $U_{\alpha}$ cover $S$ and such that

$$
S \cap U_{\alpha}=\phi_{\alpha}^{-1}\left(\mathbb{R}^{k}\right)
$$

holds for each $\alpha$. (This is possible given the definition of a sub-manifold in the text.)

Let $V_{\alpha}=S \cap U_{\alpha}$, and let $\psi_{\alpha}=\left.\phi_{\alpha}\right|_{V_{\alpha}}$. Then the $V_{\alpha}$ 's are open subsets of $S$, and the functions $\psi_{\beta} \circ \psi_{\alpha}^{-1}$ go from $\mathbb{R}^{k}$ to itself. Hence $\left\{\left(V_{\alpha}, \psi_{\alpha}\right)\right\}$ forms an atlas for $S$.

## Exercise 91

As a topological space, it is compact since it is closed (being the pre-image of the closed set $\{1\}$ under the norm function) and bounded (all points have norm less than 2).

To show that it's a submanifold, the same function as used in exercise 84 will work:

Define

$$
U_{1}^{+}=\left\{x \in \mathbb{R}^{n}: x_{1}>0\right\}
$$

and define the map

$$
\phi_{1}^{+}: U_{1}^{+} \rightarrow \mathbb{R}^{n}
$$

by mapping $\left(x_{1}, \ldots, x_{n}\right)$ to

$$
\frac{\|x\|}{x_{1}}\left(x_{1}, \ldots, x_{n}\right)
$$

$\left(U_{1}^{+}, \phi_{1}^{+}\right)$is a chart on $\mathbb{R}^{n}$ that maps $S^{n-1} \cap U_{1}^{+}$bijectively to the hyperplane

$$
\left\{x \in \mathbb{R}^{n}: x_{n}=1\right\}
$$

which is $\mathbb{R}^{n-1}$. The collection of open sets $U_{i}^{ \pm}$(with $U_{i}^{-}$defined as expected) cover $S^{n-1}$.

## Exercise 92

Let $V \subset M$ be an open subset, and let $\left\{\left(U_{\alpha}, \phi_{\alpha}\right)\right\}$ be an atlas for $M$. Then the family of open sets $U_{\alpha} \cap V$ together with the charts $\left.\phi_{\alpha}\right|_{V}$ forms a suitable family to meet the requirements of the definition of a submanifold.

## Exercise 93

This is exactly the same as exercise 90 except that $\mathbb{R}^{k}$ should be replaced everywhere by ( $\mathbb{R}^{k}$ or $\mathbf{H}^{k}$ ), roughly speaking.

## Exercise 94

Again, this is almost the same as exercise 91 , using the same map.

## Exercise 95

Let

$$
\omega=\omega_{x} d x+\omega_{y} d y
$$

be an arbitrary 1-form on $S$. Then

$$
d \omega=\partial_{x} \omega_{y}-\partial_{y} \omega_{x} d x \wedge d y
$$

so Stokes' theorem,

$$
\int_{S} d \omega=\int_{\partial S} \omega
$$

becomes

$$
\int_{S} \partial_{x} \omega_{y}-\partial_{y} \omega_{x} d x d y=\int_{\partial S}\left(\omega_{x} d x+\omega_{y} d y\right)
$$

## Exercise 96

Let $S \in \mathbb{R}^{3}$ be a 2 -dimensional compact orientable submanifold with boundary. Choose an atlas for $S$ as a submanifold. It should be possible to subdivide $S$ into a finite number of smaller 2-dimensional compact orientable submanifolds with boundary, such the $S$ is the union of these smaller parts, and the intersection of any two parts is either empty, or a 1-dimensional manifold.

Then the sum of integrating over all the boundaries of these smaller parts is the same as integrating over the boundary of $S$ since opposite integrals cancel out. Also, the sum of integrating over the surfaces of all the smaller parts yields the same answer as integrating over the whole of $S$. It follows that we only need to prove the given statement for one of the smaller parts, i.e. we can assume $S$ is such a smaller part.

Then we can choose coordinates such that $S$ lies in the plane $z=0$. Let

$$
\omega=\omega_{x} d x+\omega_{y} d y
$$

be a 1 -form on $S$. Then

$$
d \omega=\left(\partial_{x} \omega_{y}-\partial_{y} \omega_{x}\right) d x \wedge d y
$$

and Stokes' theorom implies that

$$
\int_{S}\left(\partial_{x} \omega_{y}-\partial_{y} \omega_{x}\right) d x \wedge d y=\int_{\partial S} \omega
$$

Now let $F=\left(F_{x}, F_{y}, F_{z}\right)$ be a vector field (on an open subset of $\mathbb{R}^{3}$ containing $S)$. According to the usual Stokes' theorem,

$$
\int_{S}(\nabla \times F) \cdot d S=\int_{\partial S} F \cdot d r
$$

Let

$$
\omega=F_{x} d x+F_{y} d y+F_{z} d z
$$

be a 1-form defined using the components of $F$. Given the orientation of $S$, the normal $d S$ always points in the $z$-direction. Thus

$$
(\nabla \times F) \cdot d S
$$

corresponds to the $z$-component of $d \omega$, which is

$$
\partial_{x} F_{y}-\partial_{y} F_{x}
$$

Thus the left-hand sides of the classic version and the more general version of Stokes' theorem, agree. For the right-hand side, note that $d r$ will always be orthogonal to the $z$-direction, so the $z$-component of $F$ can be ignored here as well. The right-hand sides then also agree.

## Exercise 97

In this case, let

$$
\omega=\omega_{x} d y \wedge d z+\omega_{y} d z \wedge d x+\omega_{z} d x \wedge d y
$$

be the 2-form corresponding to the vector field $F=\left(\omega_{x}, \omega_{y}, \omega_{z}\right)$. Then integrating the divergence of $F$ over the volume is clearly the same as integrating

$$
d \omega=\left(\partial_{x} \omega_{x}+\partial_{y} \omega_{y}+\partial_{z} \omega_{z}\right) d x \wedge d y \wedge d z
$$

over the volume. To show that integrating the normal of $F$ over the surface (the boundary of the volume) is the same as integrating $\omega$ over the surface, choose local coordinates such that the surface lies in the plane $z=0$. Then the normal component of $F$ is just $\omega_{z}$, and restricted to the surface, the 2-form $\omega$ becomes $\omega_{z} d x \wedge d y$, and integrating the two gives the same result.

## Exercise 98

Let $\phi$ be a map from $M$ to $N$, and let $\omega$ be a $p$-form on $N$.
Suppose $\omega$ is closed, i.e. $d \omega=0$. Then

$$
\begin{aligned}
d\left(\phi^{*} \omega\right) & =\phi^{*}(d \omega) \\
& =\phi^{*}(0) \\
& =0
\end{aligned}
$$

so $\phi^{*} \omega$ is also closed.
Suppose that $\omega$ is exact, i.e. $\omega=d \nu$, where $\nu$ is a $p-1$-form on $N$. Then

$$
\begin{aligned}
\phi^{*}(\omega) & =\phi^{*}(d \nu) \\
& =d \phi^{*}(\nu)
\end{aligned}
$$

so $\phi^{*} \omega$ is also exact.

## Exercise 99

Firstly, the linear map on $p$-forms from $\Omega^{p}\left(M^{\prime}\right)$ to $\Omega^{p}(M)$ has been defined earlier. The previous exercise shows that if we restrict this map to the closed forms $Z^{p}\left(M^{\prime}\right)$, then the image lies in $Z^{p}(M)$. So we get a map from $Z^{p}\left(M^{\prime}\right)$ to $Z^{p}(M)$. The previous exercise also shows that the kernel of this map contains the exact forms $B^{p}\left(M^{\prime}\right)$, hence it induces a map on the equivalence classes, from $H^{p}\left(M^{\prime}\right)$ to $H^{p}(M)$, as desired.

For the second part, showing that the map on the cohomology groups commutes with composition of maps follows from the fact that the pull-back map on $p$-forms commutes with composition of maps between manifolds.

